Integrated Circuits for Communication Berkeley

### **Distortion Analysis**

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#### The Origin of Distortion

## Introduction to Distortion



- Up to now we have treated amplifiers as small-signal linear circuits. Since transistors are non-linear, this assumption is only valid for extremeley small signals.
- Consider a class of memoryless non-linear amplifiers. In other words, let's neglect energy storage elements.
- This is the same as saying the output is an instantaneous function of the input. Thus the amplifier has no memory.

### **Distortion Analaysis Assumptions**

 We also assume the input/output description is sufficiently smooth and continuous as to be accurately described by a power series

$$s_o = a_1 s_i + a_2 s_i^2 + a_3 s_i^3 + \dots$$

For instance, for a BJT (Si, SiGe, GaAs) operated in forward-active region, the collector current is a smooth function of the voltage  $V_{BE}$ 





- We shift the origin by eliminating the DC signals,  $i_o = I_C I_Q$ . The input signal is then applied around the DC level  $V_{BE,Q}$ .
- Note that an ideal amplifier has a perfectly linear line.

# JFET Distortion



 JFETs are sometimes used in RF circuits. The I-V relation is also approximately square law

$$I_D = I_{DSS} \left( 1 - \frac{V_{GS}}{V_P} \right)^2$$

• The gate current (junction leakage) is typically very small  $I_G \sim 10^{12}$ A. So for all practical purposes,  $R_i = \infty$ .

# **MOSFET** Distortion



• The long-channel device also follows the square law relation (neglecting bulk charge effects)

$$I_D = \frac{1}{2} \mu C_{ox} \frac{W}{L} \left( V_{GS} - V_t \right)^2 \left( 1 + \lambda V_{DS} \right)$$

• This is assuming the device does not leave the forward active (saturation) regime.

 Short-channel devices are even more difficult due to velocity saturation and field dependent mobility. A simple model for a transistor in forward active region is given by (neglecting output resistance)

$$I_D = \frac{1}{2}\mu C_{ox} \frac{W}{L} \frac{(V_{GS} - V_t)^2}{1 + \theta(V_{GS} - V_t)}$$

• Note that the device operation near threshold is not captured by this equation.

# Single Equation MOSFET Model

• The I-V curve of a MOSFET in moderate and weak inversion is easy to describe in a "piece-meal" fashion, but difficult to capture with a single equation. One approximate single-equation relationship often used is given by

$$I_D = \frac{1}{2}\mu C_{ox} \frac{W}{L} \frac{X^2}{1+\theta X}$$

where X is given by

$$X = 2\eta rac{kT}{q} \ln \left( 1 + e^{rac{q(V_{GS} - V_t)}{2\eta kT}} 
ight)$$

• If the exponential term dominates, then  $X = V_{GS} - V_t$ , which is true for operation in strong inversion. Otherwise,  $\ln(1 + a) \approx a$ , which makes the model mimic the weak-inversion "bipolar" exponential characteristic.

# **Differential Pair**



The differential pair is an important analog and RF building block.

• For a BJT diff pair, we have  $V_i = V_{BE1} - V_{BE2}$ 

$$I_{C1,2} = I_S e^{\frac{qV_{BE1,2}}{kT}}$$

• The sum of the collector currents are equal to the current source  $I_{C1} + I_{C2} = I_{EE}$ 



• The ideal BJT diff pair I-V relationship (neglecting base and emitter resistance) is give by

$$I_o = I_{C1} - I_{C2} = \alpha I_{EE} \tanh \frac{q V_i}{2kT}$$

Notice that the output current saturates for large input voltages

#### Modeling Amplifiers with a Power Series

 For a general circuit, let's represent this behavior with a power series

$$s_o = a_1 s_i + a_2 s_i^2 + a_3 s_i^3 + \dots$$

- *a*<sub>1</sub> is the small signal gain
- The coefficients  $a_1, a_2, a_3, \ldots$  are independent of the input signal  $s_i$  but they depend on bias, temperature, and other factors.

### Harmonic Distortion

• Assume we drive the amplifier with a time harmonic signal at frequency  $\omega_1$ 

$$s_i = S_1 \cos \omega_1 t$$

• A linear amplifier would output  $s_o = a_1 S_1 \cos \omega_1 t$  whereas our amplifier generates

$$s_o = a_1 S_1 \cos \omega_1 t + a_2 S_1^2 \cos^2 \omega_1 t + a_3 S_1^3 \cos^3 \omega_1 t + \dots$$

or

$$s_o = a_1 S_1 \cos \omega_1 t + \frac{a_2 S_1^2}{2} \left(1 + \cos 2\omega_1 t\right) + \frac{a_3 S_1^3}{4} \left(\cos 3\omega_1 t + 3\cos \omega_1 t\right) + \dots$$

# Harmonic Distortion (cont)

- The term  $a_1s_1 \cos \omega_1 t$  is the wanted signal.
- Higher harmonics are also generated. These are unwanted and thus called "distortion" terms. We already see that the second-harmonic  $\cos 2\omega_1 t$  and third harmonic  $\cos 3\omega_1 t$  are generated.
- Also the second order non-linearity produces a DC shift of  $\frac{1}{2}a_2S_1^2$ .
- The third order generates both third order distortion and more fundamental. The sign of  $a_1$  and  $a_3$  determine whether the distortion product  $a_3 S_{1\frac{3}{4}}^{3\frac{3}{4}} \cos \omega_1 t$  adds or subtracts from the fundamental.
- If the signal adds, we say there is gain expansion. If it subtracts, we say there is gain compression.

## Second Harmonic Disto Waveforms



• The figure above demonstrates the waveform distortion due to second harmonic only.

# Third Harmonic Distortion Waveform



• The above figure shows the effects of the third harmonic, where we assume the third harmonic is in phase with the fundamental.

# Third Harmonic Waveform (cont)



• The above figure shows the effects of the third harmonic, where we assume the third harmonic is out of phase with the fundamental.

## General Distortion Term

• Consider the term  $\cos^n \theta = \frac{1}{2^n} (e^{j\theta} + e^{-j\theta})^n$ . Using the Binomial formula, we can expand to

$$=\frac{1}{2^n}\sum_{k=0}^n\binom{n}{k}e^{jk\theta}e^{-j(n-k)\theta}$$

• For 
$$n = 3$$
  

$$= \frac{1}{8} \left( \binom{3}{0} e^{-j3\theta} + \binom{3}{1} e^{j\theta} e^{-j2\theta} + \binom{3}{2} e^{j2\theta} e^{-j\theta} + \binom{3}{3} e^{j3\theta} \right)$$

$$= \frac{1}{8} \left( e^{-j3\theta} + e^{j3\theta} \right) + \frac{1}{8} 3 \left( e^{j\theta} + e^{-j\theta} \right) = \frac{1}{4} \cos 3\theta + \frac{3}{4} \cos \theta$$

# General Distortion Term (cont)

- We can already see that for an odd power, we will see a nice pairing up of positive and negative powers of exponentials
- For the even case, the middle term is the unpaired DC term

$$\binom{2k}{k}e^{jk\theta}e^{-jk\theta} = \binom{2k}{k}$$

- So only even powers in the transfer function can shift the DC operation point.
- The general term in the binomial expansion of  $(x + x^{-1})^n$  is given by

$$\binom{n}{k}x^{n-k}x^{-k} = \binom{n}{k}x^{n-2k}$$

## General Distortion Term (cont)

- The term  $\binom{n}{k} x^{n-2k}$  generates every other harmonic.
- If *n* is even, then only even harmonics are generated. If *n* is odd, likewise, only odd harmonics are generated.
- Recall that an "odd" function f(-x) = -f(x)(anti-symmetric) has an odd power series expansion

$$f(x) = a_1x + a_3x^3 + a_5x^5 + \dots$$

• Whereas an even function, g(-x) = g(x), has an even power series expansion

$$g(x) = a_0 + a_2 x^2 + a_4 x^4 + \dots$$

## **Output Waveform**

• In general, then, the output waveform is a Fourier series

$$v_o = \hat{V}_{o1} \cos \omega_1 t + \hat{V}_{o2} \cos 2\omega_1 t + \hat{V}_{o3} \cos 3\omega_1 t + \dots$$



#### Harmonic Distortion Metrics

• The fractional second-harmonic distortion is a commonly cited metric

$$HD_2 = rac{\text{ampl of second harmonic}}{\text{ampl of fund}}$$

• If we assume that the square power dominates the second-harmonic

$$HD_2 = rac{a_2 rac{S_1^2}{2}}{a_1 S_1}$$

or

$$HD_2 = \frac{1}{2} \frac{a_2}{a_1} S_1$$

• The fractional third harmonic distortion is given by

$$HD_3 = \frac{\text{ampl of third harmonic}}{\text{ampl of fund}}$$

• If we assume that the cubic power dominates the third harmonic

$$HD_{3} = \frac{a_{3}\frac{S_{1}}{4}}{a_{1}S_{1}}$$
$$HD_{3} = \frac{1}{4}\frac{a_{3}}{a_{1}}S_{1}^{2}$$

or

## **Output Referred Harmonic Distortion**

• In terms of the output signal  $S_{om}$ , if we again neglect gain expansion/compression, we have  $S_{om} = a_1 S_1$ 

$$HD_2 = \frac{1}{2} \frac{a_2}{a_1^2} S_{om}$$

$$HD_3 = rac{1}{4} rac{a_3}{a_1^3} S_{om}^2$$

• On a dB scale, the second harmonic increases linearly with a slope of one in terms of the output power whereas the thrid harmonic increases with a slope of 2.

 Recall that a general memoryless non-linear system will produce an output that can be written in the following form

$$\mathbf{v}_o(t) = \hat{V}_{o1} \cos \omega_1 t + \hat{V}_{o2} \cos 2\omega_1 t + \hat{V}_{o3} \cos 3\omega_1 t + \dots$$

• By Parseval's theorem, we know the total power in the signal is related to the power in the harmonics

$$\int_{T} v^{2}(t)dt = \int_{T} \sum_{j} \hat{V}_{oj} \cos(j\omega_{1}t) \sum_{k} \hat{V}_{ok} \cos(k\omega_{1}t)dt$$
$$= \sum_{j} \sum_{k} \int_{T} \hat{V}_{oj} \cos(j\omega_{1}t) \hat{V}_{ok} \cos(k\omega_{1}t)dt$$

### Power in Distortion

• By the orthogonality of the harmonics, we obtain Parseval's Them

$$\int_{\mathcal{T}} v^2(t) dt = \sum_j \sum_k rac{1}{2} \delta_{jk} \hat{V}_{oj} \hat{V}_{ok} = rac{1}{2} \sum_j \hat{V}_{oj}^2$$

• The power in the distortion relative to the fundamental power is therefore given by

$$\frac{\text{Power in Distortion}}{\text{Power in Fundamental}} = \frac{V_{o2}^2}{V_{o1}^2} + \frac{V_{o3}^2}{V_{o1}^2} + \cdots$$

$$=HD_2^2+HD_3^2+HD_4^2+\cdots$$

# Total Harmonic Distortion

• We define the *Total Harmonic Distortion* (*THD*) by the following expression

$$THD = \sqrt{HD_2^2 + HD_3^2 + \cdots}$$

- Based on the particular application, we specify the maximum tolerable *THD*
- Telephone audio can be pretty distorted (THD < 10%)
- High quality audio is very sensitive ( THD < 1% to THD < .001%)
- Video is also pretty for giving, THD < 5% for most applications
- Analog Repeaters < .001%. RF Amplifiers < 0.1%

#### Intermodulation and Crossmodulation Distortion

### Intermodulation Distortion

• So far we have characterized a non-linear system for a single tone. What if we apply two tones

$$S_{i} = S_{1} \cos \omega_{1} t + S_{2} \cos \omega_{2} t$$
$$S_{o} = a_{1}S_{i} + a_{2}S_{i}^{2} + a_{3}S_{i}^{3} + \cdots$$
$$= a_{1}S_{1} \cos \omega_{1} t + a_{1}S_{2} \cos \omega_{2} t + a_{2}(S_{i})^{2} + a_{3}(S_{i})^{3} + \cdots$$

• The second power term gives

$$a_2 S_1^2 \cos^2 \omega_1 t + a_2 S_2^2 \cos^2 \omega_2 t + 2a_2 S_1 S_2 \cos \omega_1 t \cos \omega_2 t$$

$$=a_{2}\frac{S_{1}^{2}}{2}(\cos 2\omega_{1}t+1)+a_{2}\frac{S_{2}^{2}}{2}(\cos 2\omega_{2}t+1)+a_{2}S_{1}S_{2}(\cos(\omega_{1}+\omega_{2})t-\cos(\omega_{1}-\omega_{2})t)$$

# Second Order Intermodulation

- The last term  $\cos(\omega_1 \pm \omega_2)t$  is the second-order intermodulation term
- The intermodulation distortion  $IM_2$  is defined when the two input signals have equal amplitude  $S_i = S_1 = S_2$

$$IM_2 = \frac{\text{Amp of Intermod}}{\text{Amp of Fund}} = \frac{a_2}{a_1}S_i$$

• Note the relation between  $IM_2$  and  $HD_2$ 

$$\textit{IM}_2 = 2\textit{HD}_2 = \textit{HD}_2 + 6 \text{dB}$$

# Practical Effects of IM<sub>2</sub>

- This term produces distortion at a lower frequency  $\omega_1 \omega_2$ and at a higher frequency  $\omega_1 + \omega_2$
- Example: Say the receiver bandwidth is from  $800\rm MHz-2.4GHz$  and two unwanted interfering signals appear at  $800\rm MHz$  and  $900\rm MHz.$
- Then we see that the second-order distortion will produce distortion at 100MHz and 1.7GHz. Since 1.7GHz is in the receiver band, signals at this frequency will be corrupted by the distortion.
- A weak signal in this band can be "swamped" by the distortion.
- Apparently, a "narrowband" system does not suffer from *IM*<sub>2</sub>? Or does it ?

- In a low-IF or direct conversion receiver, the signal is down-converted to a low intermediate frequency  $f_{IF}$
- Since  $\omega_1 \omega_2$  can potentially produce distortion at low frequency,  $IM_2$  is very important in such systems
- Example: A narrowband system has a receiver bandwidth of 1.9GHz 2.0GHz. A sharp input filter eliminates any interference outside of this band. The IF frequency is 1MHz
- Imagine two interfering signals appear at  $f_1 = 1.910$ GHz and  $f_2 = 1.911$ GHz. Notice that  $f_2 f_1 = f_{IF}$
- Thus the output of the amplifier/mixer generate distortion at the IF frequency, potentially disrupting the communication.

• Now let's consider the output of the cubic term

$$a_3 s_i^3 = a_3 (S_1 \cos \omega_1 t + S_2 \cos \omega_2 t)^3$$

• Let's first notice that the first and last term in the expansion are the same as the cubic distortion with a single input

$$\frac{a_3 S_{1,2}^3}{4} \left( \cos 3\omega_{1,2} t + 3\cos \omega_{1,2} t \right)$$

• The cross terms look like

$$\binom{3}{2}a_3S_1S_2^2\cos\omega_1t\cos^2\omega_2t$$

• Which can be simplified to

$$3\cos\omega_1 t\cos^2\omega_2 t = \frac{3}{2}\cos\omega_1 t(1+\cos 2\omega_2 t) =$$
$$= \frac{3}{2}\cos\omega_1 t + \frac{3}{4}\cos(2\omega_2 \pm \omega_1)$$

- The interesting term is the intermodulation at  $2\omega_2\pm\omega_1$
- By symmetry, then, we also generate a term like

$$a_3S_1^2S_2\frac{3}{4}\cos(2\omega_1\pm\omega_2)$$

• Notice that if  $\omega_1 \approx \omega_2$ , then the intermodulation  $2\omega_2 - \omega_1 \approx \omega_1$ 

## Inband IM3 Distortion



- Now we see that even if the system is narrowband, the output of an amplifier can contain in band intermodulation due to *IM*<sub>3</sub>.
- This is in contrast to *IM*<sub>2</sub> where the frequency of the intermodulation was at a lower and higher frequency. The *IM*<sub>3</sub> frequency can fall in-band for two in-band interferer

• We define  $IM_3$  in a similar manner for  $S_i = S_1 = S_2$ 

$$IM_3 = rac{\text{Amp of Third Intermod}}{\text{Amp of Fund}} = rac{3}{4} rac{a_3}{a_1} S_i^2$$

• Note the relation between  $IM_3$  and  $HD_3$ 

$$IM_3 = 3HD_3 = HD_3 + 10 \mathrm{dB}$$

### Complete Two-Tone Response



- We have so far identified the harmonics and *IM*<sub>2</sub> and *IM*<sub>3</sub> products
- A more detailed analysis shows that an order *n* non-linearity can produce intermodulation at frequencies  $j\omega_1 \pm k\omega_2$  where j + k = n
- All tones are spaced by the difference  $\omega_2-\omega_1$

#### Examples

# Distortion of BJT Amplifiers



 Consider the CE BJT amplifier shown. The biasing is omitted for clarity.

• The output voltage is simply

$$V_o = V_{CC} - I_C R_C$$

• Therefore the distortion is generated by  $I_C$  alone. Recall that

$$I_C = I_S e^{qV_{BE}/kT}$$

# BJT CE Distortion (cont)

• Now assume the input  $V_{BE} = v_i + V_Q$ , where  $V_Q$  is the bias point. The current is therefore given by

$$I_C = \underbrace{I_S e^{\frac{V_Q}{V_T}}}_{I_Q} e^{\frac{v_i}{V_T}}$$

• Using a Taylor expansion for the exponential

$$e^{x} = 1 + x + \frac{1}{2!}x^{2} + \frac{1}{3!}x^{3} + \cdots$$
$$I_{C} = I_{Q}(1 + \frac{v_{i}}{V_{T}} + \frac{1}{2}\left(\frac{v_{i}}{V_{T}}\right)^{2} + \frac{1}{6}\left(\frac{v_{i}}{V_{T}}\right)^{3} + \cdots)$$

# BJT CE Distortion (cont)

• Define the output signal  $i_c = I_C - I_Q$ 

$$i_{c} = \frac{I_{Q}}{V_{T}}v_{i} + \frac{1}{2}\left(\frac{q}{kT}\right)^{2}I_{Q}v_{i}^{2} + \frac{1}{6}\left(\frac{q}{kT}\right)^{3}I_{Q}v_{i}^{3} + \cdots$$

• Compare to  $S_o = a_1S_i + a_2S_i^2 + a_3S_i^3 + \cdots$ 

$$a_1 = rac{qI_Q}{kT} = g_m$$

$$a_{2} = \frac{1}{2} \left(\frac{q}{kT}\right)^{2} I_{Q}$$
$$a_{3} = \frac{1}{6} \left(\frac{q}{kT}\right)^{3} I_{Q}$$

• For any BJT (Si, SiGe, Ge, GaAs), we have the following result

$$HD_2 = \frac{1}{4} \frac{q\hat{v}_i}{kT}$$

- where  $\hat{v}_i$  is the peak value of the input sine voltage
- For  $\hat{v}_i = 10 \text{mV}$ ,  $HD_2 = 0.1 = 10\%$
- We can also express the distortion as a function of the output current swing  $\hat{i_c}$

$$HD_2 = \frac{1}{2} \frac{a_2}{a_1^2} S_{om} = \frac{1}{4} \frac{\hat{i}_c}{I_Q}$$

• For 
$$\frac{\hat{l}_c}{I_Q} = 0.4$$
,  $HD_2 = 10\%$ 

 $\bullet$  Let's see the maximum allowed signal for  $\mathit{IM}_3 \leq 1\%$ 

$$IM_3 = \frac{3}{4} \frac{a_3}{a_1} S_1^2 = \frac{1}{8} \left( \frac{q \hat{v}_i}{kT} \right)^2$$

• Solve  $\hat{v}_i = 7.3 \text{mV}$ . That's a pretty small voltage. For practical applications we'd like to improve the linearity of this amplifier.

### Example: Disto in Long-Ch. MOS



Ignoring the output impedance we have

$$= \frac{1}{2}\mu C_{ox} \frac{W}{L} \left\{ (V_Q - V_T)^2 + v_i^2 + 2v_i(V_Q - V_T) \right\}$$
$$= \underbrace{I_Q}_{dc} + \underbrace{\mu C_{ox} \frac{W}{L} v_i(V_Q - V_T)}_{linear} + \underbrace{\frac{1}{2}\mu C_{ox} \frac{W}{L} v_i^2}_{quadratic}$$

### Ideal Square Law Device

• An ideal square law device only generates 2nd order distortion

$$i_o = g_m v_i + \frac{1}{2} \mu C_{ox} \frac{W}{L} v_i^2$$
$$a_1 = g_m$$
$$a_2 = \frac{1}{2} \mu C_{ox} \frac{W}{L} = \frac{1}{2} \frac{g_m}{V_Q - V_T}$$
$$a_3 \equiv 0$$

• The harmonic distortion is given by

$$HD_{2} = \frac{1}{2} \frac{a_{2}}{a_{1}} v_{i} = \frac{1}{4} \frac{g_{m}}{V_{Q} - V_{T}} \frac{1}{g_{m}} v_{i} = \frac{1}{4} \frac{v_{i}}{V_{Q} - V_{T}}$$
$$HD_{3} = 0$$



• The real MOSFET device generates higher order distortion

- The output impedance is non-linear. The mobility  $\mu$  is not a constant but a function of the vertical and horizontal electric field
- We may also bias the device at moderate or weak inversion, where the device behavior is more exponential
- There is also internal *feedback*